User's Manual

FDC 4100 / 7100 / 8100 / 9100
Auto-Tune Fuzzy / PID
Process / Temperature Controller
Warning Symbol !
This Symbol calls attention to an operating procedure, practice, or the like, which, if not correctly performed or adhered to, could result in personal injury or damage to or destruction of part or all of the product and system. Do not proceed beyond a warning symbol until the indicated conditions are fully understood and met.

Use the Manual

- Installers  Read Chapter 1, 2
- System Designer  Read All Chapters
- User  Read Page 12

NOTE:
It is strongly recommended that a process should incorporate a LIMIT CONTROL like the FDC L91 which will shut down the equipment at a preset process condition in order to preclude possible damage to products or system.

Information in this user's manual is subject to change without notice.

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## Contents

### Chapter 1 Overview
- 1-1 General ........................................4
- 1-2 Ordering Code .........................7
- 1-3 Programming Port ..................8
- 1-4 Keys and Displays .................9
- 1-5 Menu Overview ..................11
- 1-6 Parameter Descriptions ....12

### Chapter 2 Installation
- 2-1 Unpacking .................................19
- 2-2 Mounting .................................19
- 2-3 Wiring precautions .................21
- 2-4 Power Wiring ..........................24
- 2-5 Sensor Installation ............24
  Guidelines.............................24
- 2-6 Sensor Input Wiring ..........25
- 2-7 Control Output Wiring ......25
- 2-8 Alarm Wiring .........................28
- 2-9 Process Retransmission ..28
- 2-10 Data Communications ....29

### Chapter 3 Programming
- 3-1 Lockout ..................................31
- 3-2 Signal Input ............................31
- 3-3 Control Outputs ..................32
- 3-4 Alarm ..................................37
- 3-5 Configure User Menu ......48
- 3-6 Ramp ..................................49
- 3-7 Dwell Timer ............................40
- 3-8 PV Shift .................................41
- 3-9 Digital Filter .........................41
- 3-10 Failure Transfer ..........42
- 3-11 Auto-tuning ......................43
- 3-12 Manual tuning ...................44
- 3-13 Manual Control .................45
- 3-14 Data communication ....47
- 3-15 PV Retransmission ......47

### Chapter 4 Calibration
- 4-1 Error Codes .........................59

### Chapter 5 Specifications
- 5-3 Specifications .....................53

### Appendix
- A-1 Error Codes ..........................59
- A-2 Warranty ............................60

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UM91001D 3
Chapter 1 Overview

1-1 General

The Fuzzy Logic plus PID microprocessor-based controller series, incorporate two bright, easy to read 4-digit LED displays, indicating process value and set point value. The Fuzzy Logic technology enables a process to reach a predetermined set point in the shortest time, with the minimum of overshoot during power-up or external load disturbance.

FDC-9100 is a 1/16 DIN size panel mount controller. FDC-7100 is a 72X72 DIN size panel mount controller. FDC-8100 is a 1/8 DIN size panel mount controller and FDC-4100 is a 1/4 DIN size panel mount controller. These units are powered by 11-26VAC/VDC or 90-250 VAC supply, incorporating a 2 amp. control relay output as standard. The second output can be used as cooling control, or an alarm. Both outputs can select triac, 5V logic output, linear current or linear voltage to drive external device. There are six types of alarm plus a dwell timer can be configured for the third output. The units are fully programmable for PT100 and thermocouple types J, K, T, E, B, R, S, N, L with no need to modify the unit. The input signal is digitized by using a 18-bit A to D converter. Its fast sampling rate, 5 scans/second, allows the unit to control fast processes.

Digital communications RS-485 or RS-232 (excluding FDC-7100) are available as an additional option. These options allow the units to be integrated with supervisory control system and software.

A programming port is available for automatic configuration, calibration and testing without the need to access the keys on front panel.

By using proprietary Fuzzy modified PID technology, the control loop will minimize the overshoot and undershoot in a shortest time. The following diagram is a comparison of results with and without Fuzzy technology.
High Accuracy

This Series controllers are manufactured with custom designed ASIC (Application Specific Integrated Circuit) technology which contains a 18-bit A to D converter for high resolution measurement (true 0.1 F resolution for thermocouple and PT100) and a 15-bit D to A converter for linear current or voltage control output. The ASIC technology provides improved operating performance, low cost, enhanced reliability and higher density.

Fast Sampling Rate

The sampling rate of the input A to D converter reaches 5 times/second. The fast sampling rate allows this series to control fast processes.

Fuzzy Control

The function of Fuzzy control is to adjust PID parameters from time to time in order to make manipulation output value more flexible and adaptive to various processes. The results is to enable a process to reach a predetermined set point in the shortest time, with the minimum of overshoot and undershoot during power-up or external load disturbance.

Digital Communication

The units are equipped with RS-485 or RS-232 interface card to provide digital communication. By using the twisted pair wires there are at most 247 units can be connected together via RS-485 interface to a host computer.
Programming Port

A programming port is used to connect the unit to a hand-held programmer or a PC for quick configuration, also can be connected to an ATE system for automatic testing & calibration.

Auto-tune

The auto-tune function allows the user to simplify initial setup for a new system. A clever algorithm is provided to obtain an optimal set of control parameters for the process, and it can be applied either as the process is warming up (cold start) or as the process has been in steady state (warm start).

Lockout Protection

According to actual security requirement, one of four lockout levels can be selected to prevent the unit from being changed abnormally.

Bumpless Transfer

Bumpless transfer allows the controller to continue to control by using its previous value as the sensor breaks. Hence, the process can be well controlled temporarily as if the sensor is normal.

Soft-start Ramp

The ramping function is performed during power up as well as any time the set point is changed. It can be ramping up or ramping down. The process value will reach the set point with a predetermined constant rate.

Digital Filter

A first order low pass filter with a programmable time constant is used to improve the stability of process value. This is particularly useful in certain application where the process value is too unstable to be read.

SEL Function

The units have the flexibility for user to select those parameters which are most significant to him and put these parameters in the front of display sequence. There are at most 8 parameters can be selected to allow the user to build his own display sequence.
**Power Input**

4: 90 - 250 VAC, 50/60 Hz  
5: 11 - 26 VAC or VDC  
9: Special Order

**Signal Input**

1: Standard Input  
   Thermocouple: J, K, T, E, B, R, S, N, L  
   RTD: PT100 DIN, PT100 JIS  
2: 0 - 60 mV  
3: 0 - 1 V  
4: 0 - 5 V  
5: 1 - 5 V  
6: 4 - 20 mA  
7: 0 - 20 mA  
8: 0 - 10 V  
9: Special Order

**Output 1**

0: None  
1: Relay rated 2A/240VAC  
2: Pulsed voltage to drive SSR, 5V/30mA  
3: Isolated 4 - 20mA / 0 - 20mA  
4: Isolated 1 - 5V / 0 - 5V  
5: Isolated 0 - 10V  
6: Triac output 1A / 240VAC, SSR  
C: Pulsed voltage to drive SSR, 14V/40mA  
9: Special Order

**Output 2**

0: None  
1: Form C relay 2A/240VAC  
9: Special order

**Communications**

0: None  
1: RS-485 interface  
2: RS-232 interface (not available for 7100)  
3: Retransmit 4-20mA / 0-20mA  
4: Retransmit 1-5V / 0-5V  
5: Retransmit 0-10V  
9: Special order

**Alarm**

0: None  
1: Form A relay 2A/240VAC  
9: Special order

**Options**

0: Panel mount IP50 standard  
1: Panel mount IP65 water resistant rubber installed  
2: DIN Rail mount with IP50 (for 9100 only)  
3: DIN Rail mount with IP65 (for 9100 only)  

**Output 1 (Box) Options**

C: Pulsed voltage to drive SSR, 14V/40mA  
A: Special order

**Output 2 (Box) Options**

C: Pulsed voltage to drive SSR, 14V/40mA  
A: Special order
A special connector can be used to touch the programming port which is connected to a PC for automatic configuration, also can be connected to an ATE system for automatic calibration and testing.

The programming port is used for off-line automatic setup and testing procedures only. Do NOT attempt to make any connection to these pins when the unit is in normal operation.
1- 4 Keys and Displays

KEYPAD OPERATION

SCROLL KEY :  
This key is used to select a parameter to be viewed or adjusted.

UP KEY :  
This key is used to increase the value of selected parameter.

DOWN KEY :  
This key is used to decrease the value of selected parameter.

RESET KEY :  
This key is used to:
1. Revert the display to display the process value.
2. Reset the latching alarm, once the alarm condition is removed.
3. Stop the manual control mode, auto-tuning mode and calibration mode.
4. Clear the message of communication error and auto-tuning error.
5. Restart the dwell timer when the dwell timer has been time out.
6. Enter the manual control menu during failure mode occurs.

ENTER KEY : Press  for 3 seconds or longer .
Press  for 3 seconds to:
1. Enter setup menu. The display shows  .
2. Enter manual control mode during manual control mode  is selected.
3. Enter auto-tuning mode during auto-tuning mode  is selected.
4. Perform calibration to a selected parameter during the calibration procedure.
Press  for 4.2 seconds to select manual control mode.
Press  for 5.4 seconds to select auto-tuning mode.
Press  for 6.6 seconds to select calibration mode.
Table 1.1 Display Form of Characters

<table>
<thead>
<tr>
<th>A</th>
<th>R</th>
<th>E</th>
<th>E</th>
<th>I</th>
<th>N</th>
<th>S</th>
<th>S</th>
<th>X</th>
</tr>
</thead>
<tbody>
<tr>
<td>B</td>
<td>b</td>
<td>F</td>
<td>F</td>
<td>J</td>
<td>J</td>
<td>O</td>
<td>T</td>
<td>Y</td>
</tr>
<tr>
<td>C</td>
<td>C</td>
<td>G</td>
<td>G</td>
<td>K</td>
<td>k</td>
<td>P</td>
<td>P</td>
<td>U</td>
</tr>
<tr>
<td>c</td>
<td>c</td>
<td>H</td>
<td>H</td>
<td>L</td>
<td>L</td>
<td>Q</td>
<td>V</td>
<td>?</td>
</tr>
<tr>
<td>D</td>
<td>d</td>
<td>h</td>
<td>h</td>
<td>M</td>
<td>M</td>
<td>R</td>
<td>r</td>
<td>W</td>
</tr>
</tbody>
</table>

\(\wedge\): Confused Character

Display program code of the product for 2.5 seconds.

The left diagram shows program no. 6 for FDC-9100 with version 12. The program no. for FDC-7100 is 13, for FDC-8100 is 11 and for FDC-4100 is 12.

Figure 1.4 Display of Initial Stage
1-5 Menu Overview

**User menu**

- PV, SV
- SP1
- SP2
- SP3
- INPT
- UNIT
- DP
- PB
- TI
- TD
- RJ
- CYC1
- ADDR
- LOCK
- INPT
- UNIT
- DP
- INLO
- INHI
- SP1L
- SP1H
- SHIF
- FILT
- PB
- TI
- TD
- OUT1
- O1TY
- O1FT
- O1HY
- CYC1
- OFST
- RAMP
- RR
- OUT2
- O2TY
- O2FT
- O2HY
- CYC2
- CPB
- DB
- ALFN
- ALMD
- ALHY
- ALFT
- COMM
- ADDR
- BAUD
- DATA
- PARI
- STOP
- SEL1
- SEL2
- SEL3
- SEL4
- SEL5
- SEL6
- SEL7
- SEL8

**Setup menu**

- 3 sec.
- 4.2 sec.
- 5.4 sec.
- 6.6 sec.
- 7.8 sec.

**Manual Mode**

- Press [ ] for 3 seconds to start manual control.

**Auto-tuning Mode**

- Release then press for 3 seconds to start auto-tuning mode.

**Calibration Mode**

- Press [ ] for 3 seconds to perform calibration.

⚠️ Apply these modes will break the control loop and change some of the previous setting data. Make sure that if the system is allowable to apply these modes.

*1: The flow chart shows a complete listing of all parameters. For actual application the number of available parameters depends on setup conditions, and should be less than that shown in the flow chart.

*2: You can select at most 8 parameters put in the user menu by using SEL1 ~ SEL8 contained at the bottom of setup menu.

*3: Release [ ], press [ ] again for 2 seconds or longer (but not longer than 3 seconds), then release to enter the calibration menu.

The user menu shown in the flow chart is corresponding to the default setting for the SEL parameters SEL1 to SEL8. SP3 will be hidden if NONE is selected for ALFN. SP2 will be hidden if alarm function is not selected for OUT2. The unused parameter will be hidden even if it is selected by SEL parameters.
## 1-6 Parameter Descriptions

<table>
<thead>
<tr>
<th>Parameter Notation</th>
<th>Parameter Description</th>
<th>Range</th>
<th>Default Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>SP1</td>
<td>Set point for output 1</td>
<td>Low: SP1L High: SP1H</td>
<td>25.0 °C (77.0 °F)</td>
</tr>
<tr>
<td>SP2</td>
<td>Set point for output 2 when output 2 performs alarm function</td>
<td>Low: -19999 High: 45536</td>
<td>10.0 °C (18.0 °F)</td>
</tr>
<tr>
<td>SP3</td>
<td>Set point for alarm or dwell timer output</td>
<td>Low: -19999 High: 45536</td>
<td>10.0 °C (18.0 °F)</td>
</tr>
</tbody>
</table>
| LOCK               | Select parameters to be locked                 | 0 : **nonE** : No parameter is locked  
1 : **SET** : Setup data are locked  
2 : **USER** : Setup data and User data except Set point are locked  
3 : **ALL** : All data are locked | 0                      |
| INPT               | Input sensor selection                         |                            | 1 (0)                  |

**NOTE:**

Input Selection 11 - 17 of Linear (ma/VDC) Require special order only See Matrix Page 8.

**Input Selection:**

- 0 **J**.**EC** : J type thermocouple
- 1 **E**.**EC** : K type thermocouple
- 2 **T**.**EC** : T type thermocouple
- 3 **E**.**EC** : E type thermocouple
- 4 **B**.**EC** : B type thermocouple
- 5 **R**.**EC** : R type thermocouple
- 6 **S**.**EC** : S type thermocouple
- 7 **N**.**EC** : N type thermocouple
- 8 **L**.**EC** : L type thermocouple
- 9 **PT100** : PT 100 ohms DIN curve
- 10 **PT100** : PT 100 ohms JIS curve
- 11 **4-20** : 4 - 20 mA linear current input
- 12 **0-20** : 0 - 20 mA linear current input
- 13 **0-60** : 0 - 60 mV linear millivolt input
- 14 **0-1V** : 0 - 1V linear voltage input
- 15 **0-5V** : 0 - 5V linear voltage input
- 16 **1-5V** : 1 - 5V linear voltage input
- 17 **0-10** : 0 - 10V linear voltage input
<table>
<thead>
<tr>
<th>Parameter Notation</th>
<th>Parameter Description</th>
<th>Range</th>
<th>Default Value</th>
</tr>
</thead>
</table>
| UNIT               | Input unit selection                   | 0  $^\circ C$ : Degree C unit  
                         | 1  $^\circ F$ : Degree F unit  
                         | 2  $^\circ F$ : Process unit  | 0  (1)         |
| DP                 | Decimal point selection                | 0  $^\circ C$ : No decimal point  
                         | 1  1-dP : 1 decimal digit  
                         | 2  2-dP : 2 decimal digits  
                         | 3  3-dP : 3 decimal digits  | 1             |
| INLO               | Input low sale value                   | Low: -19999 High: 45486     | -17.8 C (0 F) |
| INHI               | Input high scale value                 | Low: INLO+50 High: 45536    | 93.3 C (200.0 F) |
| SP1L               | Low limit of set point value           | Low: -19999 High: 45536     | -17.8 C (0 F) |
| SP1H               | High limit of set point value          | Low: SP1L High: 45536       | 537.8 C (1000 F) |
| SHIF               | PV shift (offset) value                | Low: -200.0 C (-360.0 F) High: 200.0 C (360.0 F) | 0.0           |
| FILT               | Filter damping time constant of PV     | 0  0 : 0 second time constant  
                         | 1  0.2 : 0.2 second time constant  
                         | 2  0.5 : 0.5 second time constant  
                         | 3  1 : 1 second time constant  
                         | 4  2 : 2 seconds time constant  
                         | 5  5 : 5 seconds time constant  
                         | 6  10 : 10 seconds time constant  
                         | 7  20 : 20 seconds time constant  
                         | 8  30 : 30 seconds time constant  
<pre><code>                     | 9  60 : 60 seconds time constant  | 2             |
</code></pre>
<table>
<thead>
<tr>
<th>Parameter Notation</th>
<th>Parameter Description</th>
<th>Range</th>
<th>Default Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>PB</td>
<td>Proportional band value</td>
<td>Low: 0</td>
<td>10.0 °C (18.0 °F)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>High: 500.0 °C (900.0 °F)</td>
<td></td>
</tr>
<tr>
<td>TI</td>
<td>Integral time value</td>
<td>Low: 0</td>
<td>100</td>
</tr>
<tr>
<td></td>
<td></td>
<td>High: 1000 sec</td>
<td></td>
</tr>
<tr>
<td>TD</td>
<td>Derivative time value</td>
<td>Low: 0</td>
<td>25.0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>High: 360.0 sec</td>
<td></td>
</tr>
<tr>
<td>OUT1</td>
<td>Output 1 function</td>
<td></td>
<td>0</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>O1TY</td>
<td>Output 1 signal type</td>
<td></td>
<td>0</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>O1FT</td>
<td>Output 1 failure transfer mode</td>
<td>Select BPLS (bumpless transfer) or 0.0 ~ 100.0 % to continue output 1 control function as the unit fails, or select OFF (0) or ON (1) for ON-OFF control.</td>
<td>0</td>
</tr>
<tr>
<td>O1HY</td>
<td>Output 1 ON-OFF control hysteresis</td>
<td>Low: 0.1</td>
<td>0.1 °C (0.2 °F)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>High: 50.0 °C (90.0 °F)</td>
<td></td>
</tr>
<tr>
<td>CYC1</td>
<td>Output 1 cycle time</td>
<td>Low: 0.1</td>
<td>18.0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>High: 90.0 sec.</td>
<td></td>
</tr>
<tr>
<td>OFST</td>
<td>Offset value for P control</td>
<td>Low: 0</td>
<td>25.0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>High: 100.0 %</td>
<td></td>
</tr>
<tr>
<td>RAMP</td>
<td>Ramp function selection</td>
<td>0 : No Ramp Function</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 : Use unit/minute as Ramp Rate</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 : Use unit/hour as Ramp Rate</td>
<td></td>
</tr>
<tr>
<td>Parameter Notation</td>
<td>Parameter Description</td>
<td>Range</td>
<td>Default Value</td>
</tr>
<tr>
<td>--------------------</td>
<td>-----------------------------------------------</td>
<td>----------------------------</td>
<td>---------------</td>
</tr>
<tr>
<td>RR</td>
<td>Ramp rate</td>
<td>Low: 0</td>
<td>0.0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>High: 500.0 C (900.0 F)</td>
<td></td>
</tr>
<tr>
<td>OUT2</td>
<td>Output 2 function</td>
<td>0 : Output 2 No Function</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 : Deviation High Alarm</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>3 : Deviation Low Alarm</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>6 : Process High Alarm</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>7 : Process Low Alarm</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>8 : Cool : Cooling PID Function</td>
<td></td>
</tr>
<tr>
<td>O2TY</td>
<td>Output 2 signal type</td>
<td>0 : Relay output</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 : Solid state relay drive output</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 : Solid state relay output</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>3 : 4-20 mA current module</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>4 : 0-20 mA current module</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>5 : 0-1V voltage module</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>6 : 0-5V voltage module</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>7 : 1-5V voltage module</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>8 : 0-10V voltage module</td>
<td></td>
</tr>
<tr>
<td>O2FT</td>
<td>Output 2 failure transfer mode</td>
<td>Select BPLS (bumpless transfer) or 0.0 ~ 100.0 % to continue output 2 control function as the unit fails, or select ON (0) or OFF (1) for alarm function.</td>
<td>0</td>
</tr>
<tr>
<td>O2HY</td>
<td>Output 2 hysteresis value when output 2 performs alarm function</td>
<td>Low: 0.1</td>
<td>0.1 C (0.2 F)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>High: 50.0 C (90.0 F)</td>
<td></td>
</tr>
<tr>
<td>CYC2</td>
<td>Output 2 cycle time</td>
<td>Low: 0.1</td>
<td>18.0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>High: 90.0 sec.</td>
<td></td>
</tr>
<tr>
<td>CPB</td>
<td>Cooling proportional band value</td>
<td>Low: 50</td>
<td>100</td>
</tr>
<tr>
<td></td>
<td></td>
<td>High: 300 %</td>
<td></td>
</tr>
<tr>
<td>Parameter Notation</td>
<td>Parameter Description</td>
<td>Range</td>
<td>Default Value</td>
</tr>
<tr>
<td>--------------------</td>
<td>----------------------------------------</td>
<td>----------------</td>
<td>---------------</td>
</tr>
<tr>
<td>DB</td>
<td>Heating-cooling dead band (negative value = overlap)</td>
<td>Low: -36.0</td>
<td>High: 36.0 %</td>
</tr>
<tr>
<td>ALFN</td>
<td>Alarm function for alarm output</td>
<td></td>
<td>2</td>
</tr>
<tr>
<td>ALMD</td>
<td>Alarm operation mode</td>
<td></td>
<td>0</td>
</tr>
<tr>
<td>ALHY</td>
<td>Hysteresis control of alarm</td>
<td>Low: 0.1</td>
<td>High: 50.0 C</td>
</tr>
<tr>
<td>ALFT</td>
<td>Alarm failure transfer mode</td>
<td></td>
<td>0</td>
</tr>
<tr>
<td>COMM</td>
<td>Communication function</td>
<td></td>
<td>1</td>
</tr>
<tr>
<td>Parameter Notation</td>
<td>Parameter Description</td>
<td>Range</td>
<td>Default Value</td>
</tr>
<tr>
<td>-------------------</td>
<td>------------------------------------------------------------</td>
<td>------------------------</td>
<td>---------------</td>
</tr>
<tr>
<td>ADDR</td>
<td>Address assignment of digital communication</td>
<td>Low: 1 High: 255</td>
<td></td>
</tr>
<tr>
<td>BAUD</td>
<td>Baud rate of digital communication</td>
<td>0 2.4 : 2.4 Kbits/s baud rate</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 4.8 : 4.8 Kbits/s baud rate</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 9.6 : 9.6 Kbits/s baud rate</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>3 14.4 : 14.4 Kbits/s baud rate</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>4 19.2 : 19.2 Kbits/s baud rate</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>5 28.8 : 28.8 Kbits/s baud rate</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>6 38.4 : 38.4 Kbits/s baud rate</td>
<td></td>
</tr>
<tr>
<td>DATA</td>
<td>Data bit count of digital communication</td>
<td>0 7b, e : 7 data bits</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 8b, e : 8 data bits</td>
<td></td>
</tr>
<tr>
<td>PARI</td>
<td>Parity bit of digital communication</td>
<td>0 EvEn : Even parity</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 odd : Odd parity</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 nonE : No parity bit</td>
<td></td>
</tr>
<tr>
<td>STOP</td>
<td>Stop bit count of digital communication</td>
<td>0 1b, e : One stop bit</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 2b, e : Two stop bits</td>
<td></td>
</tr>
<tr>
<td>RELO</td>
<td>PV Retranmission Low Value</td>
<td>Low: -19999 High: 45486</td>
<td></td>
</tr>
<tr>
<td>REHI</td>
<td>PV Retranmission High Value</td>
<td>Low: -19999 High: 45486</td>
<td></td>
</tr>
<tr>
<td>SEL1</td>
<td>Select 1'st parameter for user menu</td>
<td>0 nonE : No parameter selected</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 LocE : LOCK is put ahead</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 NumE : INPT is put ahead</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>3 UniE : UNIT is put ahead</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>4 DP : DP is put ahead</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>5 SHi : SHIF is put ahead</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>6 PB : PB is put ahead</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>7 Ti : TI is put ahead</td>
<td></td>
</tr>
</tbody>
</table>

UM91001D
<table>
<thead>
<tr>
<th>Parameter Notation</th>
<th>Parameter Description</th>
<th>Range</th>
<th>Default Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>SEL1</td>
<td>Select 1st parameter for user menu</td>
<td>8 ( \text{td} ) : TD is put ahead</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td></td>
<td>9 ( o_1 \text{HY} ) : O1HY is put ahead</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>10 ( \text{CYC1} ) : CYC1 is put ahead</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>11 ( \text{OFST} ) : OFST is put ahead</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>12 ( r_r ) : RR is put ahead</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>13 ( o_2 \text{HY} ) : O2HY is put ahead</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>14 ( \text{CYC2} ) : CYC2 is put ahead</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>15 ( \text{CPb} ) : CPB is put ahead</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>16 ( \text{db} ) : DB is put ahead</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>17 ( \text{Addr} ) : ADDR is put ahead</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>18 ( \text{ALHY} ) : ALHY is put ahead</td>
<td></td>
</tr>
<tr>
<td>SEL2</td>
<td>Select 2nd parameter for user menu</td>
<td>Same as SEL1</td>
<td>3</td>
</tr>
<tr>
<td>SEL3</td>
<td>Select 3rd parameter for user menu</td>
<td>Same as SEL1</td>
<td>4</td>
</tr>
<tr>
<td>SEL4</td>
<td>Select 4th parameter for user menu</td>
<td>Same as SEL1</td>
<td>6</td>
</tr>
<tr>
<td>SEL5</td>
<td>Select 5th parameter for user menu</td>
<td>Same as SEL1</td>
<td>7</td>
</tr>
<tr>
<td>SEL6</td>
<td>Select 6th parameter for user menu</td>
<td>Same as SEL1</td>
<td>8</td>
</tr>
<tr>
<td>SEL7</td>
<td>Select 7th parameter for user menu</td>
<td>Same as SEL1</td>
<td>10</td>
</tr>
<tr>
<td>SEL8</td>
<td>Select 8th parameter for user menu</td>
<td>Same as SEL1</td>
<td>17</td>
</tr>
</tbody>
</table>
Chapter 2 Installation

⚠️ Dangerous voltages capable of causing death are sometimes present in this instrument. Before installation or beginning any troubleshooting procedures the power to all equipment must be switched off and isolated. Units suspected of being faulty must be disconnected and removed to a properly equipped workshop for testing and repair. Component replacement and internal adjustments must be made by a qualified maintenance person only.

⚠️ To minimize the possibility of fire or shock hazards, do not expose this instrument to rain or excessive moisture.

⚠️ Do not use this instrument in areas under hazardous conditions such as excessive shock, vibration, dirt, moisture, corrosive gases or oil. The ambient temperature of the areas should not exceed the maximum rating specified in Chapter 5.

2-1 Unpacking
Upon receipt of the shipment remove the unit from the carton and inspect the unit for shipping damage.
If any damage due to transit, report and claim with the carrier.
Write down the model number, serial number, and date code for future reference when corresponding with our service center. The serial number (S/N) and date code (D/C) are labeled on the box and the housing of control.

2-2 Mounting
Make panel cutout to dimension shown in Figure 2.1.
Take both mounting clamps away and insert the controller into panel cutout. Install the mounting clamps back. Gently tighten the screws in the clamp till the controller front panels is fitted snugly in the cutout.
Figure 2.1 Mounting Dimensions
2 - 3 Wiring Precautions

* Before wiring, verify the label for correct model number and options. Switch off the power while checking.

* Care must be taken to ensure that maximum voltage rating specified on the label are not exceeded.

* It is recommended that power of these units to be protected by fuses or circuit breakers rated at the minimum value possible.

* All units should be installed inside a suitably grounded metal enclosure to prevent live parts being accessible from human hands and metal tools.

* All wiring must conform to appropriate standards of good practice and local codes and regulations. Wiring must be suitable for voltage, current, and temperature rating of the system.

* Beware not to over-tighten the terminal screws.

* Unused control terminals should not be used as jumper points as they may be internally connected, causing damage to the unit.

* Verify that the ratings of the output devices and the inputs as specified in Chapter 5 are not exceeded.
**Figure 2.2**
Lead Termination for FDC-4100, FDC-8100 and FDC-7100

**Figure 2.3**
Lead Termination for FDC-9100

**Figure 2.4**
Rear Terminal Connection for FDC-4100 and FDC-8100
**Figure 2.5**
Rear Terminal Connection for FDC-7100

PV Retrans
RS-232: TXD RXD COM
RS-485: TX1 TX2

**Figure 2.6**
Rear Terminal Connection for FDC-9100

90-250VAC
47-63 Hz
12VA
2 - 4 Power Wiring

The controller is supplied to operate at 11-26 VAC / VDC or 90-250 VAC. Check that the installation voltage corresponds with the power rating indicated on the product label before connecting power to the controller.

![Power Supply Connections](image_url)

**Figure 2.7** Power Supply Connections

⚠️ This equipment is designed for installation in an enclosure which provides adequate protection against electric shock. The enclosure must be connected to earth ground.

Local requirements regarding electrical installation should be rigidly observed. Consideration should be given to prevent from unauthorized person access to the power terminals.

2-5 Sensor Installation Guidelines

Proper sensor installation can eliminate many problems in a control system. The probe should be placed so that it can detect any temperature change with minimal thermal lag. In a process that requires fairly constant heat output, the probe should be placed closed to the heater. In a process where the heat demand is variable, the probe should be closed to the work area. Some experiments with probe location are often required to find this optimum position.

In a liquid process, addition of a stirrer will help to eliminate thermal lag. Since the thermocouple is basically a point measuring device, placing more than one thermocouple in parallel can provide an average temperature readout and produce better results in most air heated processes.
Proper sensor type is also a very important factor to obtain precise measurements. The sensor must have the correct temperature range to meet the process requirements. In special processes the sensor might need to have different requirements such as leak-proof, anti-vibration, antiseptic, etc.

Standard sensor limits of error are +/-4 degrees F (+/- 2 degrees C) or 0.75% of sensed temperature (half that for special) plus drift caused by improper protection or an over-temperature occurrence. This error is far greater than controller error and cannot be corrected on the sensor except by proper selection and replacement.

### 2-6 Sensor Input Wiring

<table>
<thead>
<tr>
<th>FDC-4100</th>
<th>FDC-8100</th>
<th>FDC-7100</th>
<th>FDC-9100</th>
</tr>
</thead>
<tbody>
<tr>
<td>PTA</td>
<td>18</td>
<td>TC+, V+</td>
<td>12</td>
</tr>
<tr>
<td></td>
<td>19</td>
<td>PTB, mA+</td>
<td>13</td>
</tr>
<tr>
<td>TC-, V-</td>
<td>20</td>
<td>PTB, mA-</td>
<td>14</td>
</tr>
</tbody>
</table>

**Figure 2.8** Sensor Input Wiring

### 2-7 Control Output 1 Wiring

<table>
<thead>
<tr>
<th>FDC-4100</th>
<th>FDC-8100</th>
<th>FDC-7100</th>
<th>FDC-9100</th>
</tr>
</thead>
<tbody>
<tr>
<td>3</td>
<td>4</td>
<td>8</td>
<td>9</td>
</tr>
</tbody>
</table>

**Figure 2.9** Output 1 Relay or Triac (SSR) to Drive Load
2-7 Control Output 1 Wiring (Cont’d)

**Figure 2.10** Output 1 Pulsed +5 VDC Voltage to Drive SSR

**Figure 2.11** Output 1 Linear Current

**Figure 2.12** Output 1 Linear Voltage
**Control Output 2 Wiring**

**Figure 2.13**
Output 2 Relay or Triac (SSR) to Drive Load

**Figure 2.14**
Output 2 Pulsed Voltage to Drive SSR

**Figure 2.15**
Output 2 Linear Current
Control Output 2 Wiring (Cont’d)

2-8 Alarm Wiring

2-9 Process Retransmission

FDC-9100/8100/4100

Output to Recorder, PLC, Etc.

Load Resistance: 0 - 500 ohms (for current output)
10 K ohms minimum (for voltage output)

FDC-7100

Output to Recorder, PLC, Etc.

Load Resistance: 0 - 500 ohms (for current output)
10 K ohms minimum (for voltage output)

Figure 2.18 Retransmission Output Wiring
2-10 Data Communication

FDC-4100  FDC-8100  FDC-9100  FDC-7100
TX1  13  10  TX1
TX2  14  11  TX2
Twisted-Pair Wire

FDC-4100  FDC-8100  FDC-9100  FDC-7100
TX1  13  10  TX1
TX2  14  11  TX2

RS-485 to RS-232 network adaptor
SNA10A or SNA10B

TX1  TX2

RS-232

PC

Max. 247 units can be linked

Terminator 220 ohms / 0.5W

Figure 2.19  RS-485 Wiring
If you use a conventional 9-pin RS-232 cable instead of CC94-1, the cable must be modified according to the following circuit.
Chapter 3 Programming

Press \( \text{ } \) for 3 seconds and release to enter setup menu. Press \( \text{ } \) to select the desired parameter. The upper display indicates the parameter symbol, and the lower display indicates the selected value of parameter.

3-1 Lockout

There are four security levels can be selected by using LOCK parameter.

If **NONE** is selected for LOCK, then no parameter is locked.
If **SET** is selected for LOCK, then all setup data are locked.
If **USER** is selected for LOCK, then all setup data as well as user data (refer to section 1-5) except set point are locked to prevent from being changed.
If **ALL** is selected for LOCK, then all parameters are locked to prevent from being changed.

3-2 Signal Input

INPT: Selects the sensor type or signal type for signal input.
  - (RTD) PT.DN, PT.JS
  - (linear) 4-20, 0-20, 0-60, 0-1V, 0-5V, 1-5V, 0-10

UNIT: Selects the process unit
  - Range: C, F, PU (process unit). If the unit is neither C nor F, then selects PU.

DP: Selects the resolution of process value.
  - Range: (for T/C and RTD) NO.DP, 1-DP
  - (for linear) NO.DP, 1-DP, 2-DP, 3-DP

INLO: Selects the low scale value for the linear type input.

INHI: Selects the high scale value for the linear type input.

**How to use INLO and INHI:**

IA unit ordered with 4 - 20 mA is setup as INPT = 4-20, then if SL specifies the input signal low (ie. 4 mA), SH specifies the input signal high (ie. 20 mA), S specifies the current input signal value, the conversion curve of the process value is shown as follows:
Formula: \[ PV = INLO + \left( \frac{INHI - INLO}{SH - SL} \right) \frac{S - SL}{SH - SL} \]

Example: A 4-20 mA current loop pressure transducer with range 0 - 15 kg/cm\(^2\) is connected to input, then perform the following setup:

\[ \text{INPT} = 4 - 20 \quad \text{INLO} = 0.00 \]
\[ \text{INHI} = 15.00 \quad \text{DP} = 2 - \text{DP} \]

Of course, you may select other value for DP to alter the resolution.

### 3-3 Control Outputs

There are 4 kinds of control modes can be configured as shown in Table 3.1

**Table 3.1 Heat-Cool Control Setup Value**

<table>
<thead>
<tr>
<th>Control Modes</th>
<th>OUT1</th>
<th>OUT2</th>
<th>O1HY</th>
<th>O2HY</th>
<th>CPB</th>
<th>DB</th>
</tr>
</thead>
<tbody>
<tr>
<td>Heat only</td>
<td>REVR</td>
<td>×</td>
<td>☆</td>
<td>×</td>
<td>×</td>
<td>×</td>
</tr>
<tr>
<td>Cool only</td>
<td>DIRT</td>
<td>×</td>
<td>☆</td>
<td>×</td>
<td>×</td>
<td>×</td>
</tr>
<tr>
<td>Heat: PID</td>
<td>REVR</td>
<td>DE.HI</td>
<td>×</td>
<td>O</td>
<td>×</td>
<td>×</td>
</tr>
<tr>
<td>Cool: ON-OFF</td>
<td>REVR</td>
<td>COOL</td>
<td>×</td>
<td>×</td>
<td>O</td>
<td>O</td>
</tr>
<tr>
<td>Heat: PID</td>
<td>REVR</td>
<td>COOL</td>
<td>×</td>
<td>×</td>
<td>O</td>
<td>O</td>
</tr>
<tr>
<td>Cool: PID</td>
<td>REVR</td>
<td>COOL</td>
<td>×</td>
<td>×</td>
<td>O</td>
<td>O</td>
</tr>
</tbody>
</table>

×: Don't care
☆: Required if ON-OFF control is configured
○: Adjust to meet process requirements
Heat Only ON-OFF Control: Select REVR for OUT1, Set PB to 0, O1HY is used to adjust dead band for ON-OFF control, The output 1 hysteresis (O1HY) is enabled in case of PB = 0. The heat only on-off control function is shown in the following diagram:

![Diagram of heat only ON-OFF control](image)

Figure 3.2 Heat Only ON-OFF Control

The ON-OFF control may introduce excessive process oscillation even if hysteresis is minimized to the smallest. If ON-OFF control is set (ie. PB = 0), TI, TD, CYC1, OFST, CYC2, CPB, DB will be hidden and have no function to the system. The auto-tuning mode and bumpless transfer will be disabled too.

Heat only P (or PD) control: Select REVR for OUT1, set TI to 0, OFST is used to adjust the control offset (manual reset). O1HY is hidden if PB is not equal to 0. OFST Function: OFST is measured by % with range 0 - 100.0%. In the steady state (ie. process has been stabilized) if the process value is lower than the set point a definite value, say 5 LC, while 20 LC is used for PB, that is lower 25%,
then increase OFST 25 %, and vice versa. After adjusting OFST value, the process value will be varied and eventually, coincide with set point. Using the P control ( TI set to 0 ), the auto-tuning is disabled. Refer to section 3-12 " manual tuning " for the adjustment of PB and TD. Manual reset ( adjust OFST ) is not practical because the load may change from time to time and often need to adjust OFST repeatedly. The PID control can avoid this situation.

Heat only PID control: Selecting REVR for OUT1, PB and TI should not be zero. Operate auto-tuning for the new process, or set PB, TI and TD with historical values. See section 3-11 for auto-tuning operation. If the control result is still unsatisfactory, then use manual tuning to improve the control. See section 3-12 for manual tuning. The unit contains a very clever PID and Fuzzy algorithm to achieve a very small overshoot and very quick response to the process if it is properly tuned.

Cool only control: ON-OFF control, P ( PD ) control and PID control can be used for cool control. Set OUT1 to DIRT ( direct action ). The other functions for cool only ON-OFF control, cool only P ( PD ) control and cool only PID control are same as descriptions for heat only control except that the output variable ( and action ) for the cool control is inverse to the heat control.

NOTE: The ON-OFF control may result excessive overshoot and undershoot problems in the process. The P ( or PD ) control will result in a deviation process value from the set point. It is recommended to use PID control for the Heat-Cool control to produce a stable and zero offset process value.

Other Setup Required: O1TY, CYC1, O2TY, CYC2, O1FT, O2FT
O1TY & O2TY are set in accordance with the types of OUT1 & OUT2 installed. CYC1 & CYC2 are selected according to the output 1 type ( O1TY ) & output 2 type ( O2TY ). Generally, selects 0.5 ~ 2 sec. for CYC1, if SSRD or SSR is used for O1TY; 10 ~ 20 sec. if relay is used for O1TY, and CYC1 is ignored if linear output is used. Similar condition is applied for CYC2 selection.
You can use the auto-tuning program for the new process or directly set the appropriate values for PB, TI & TD according to the historical records for the repeated systems. If the control behavior is still inadequate, then use manual tuning to improve the control. See section 3-12 for manual tuning.

CPB Programming: The cooling proportional band is measured by % of PB with range 50~300. Initially set 100% for CPB and examine the cooling effect. If cooling action should be enhanced then decrease CPB, if cooling action is too strong then increase CPB. The value of CPB is related to PB and its value remains unchanged throughout the auto-tuning procedures.

Adjustment of CPB is related to the cooling media used. For air is used as cooling media, adjust CPB at 100(%). For oil is used as cooling media, adjust CPB at 125(%). For water is used as cooling media, adjust CPB at 250(%).

DB Programming: Adjustment of DB is dependent on the system requirements. If more positive value of DB (greater dead band) is used, an unwanted cooling action can be avoided but an excessive overshoot over the set point will occur. If more negative value of DB (greater overlap) is used, an excessive overshoot over the set point can be minimized but an unwanted cooling action will occur. It is adjustable in the range -36.0% to 36.0% of PB. A negative DB value shows an overlap area over which both outputs are active. A positive DB value shows a dead band area over which neither output is active.

Output 2 ON-OFF Control (Alarm function): The output 2 can also be configured as alarm function. There are 4 kinds of alarm functions can be selected for output 2, these are: DE.HI (deviation high alarm), DE.LO (deviation low alarm), PV.HI (process high alarm) and PV.LO (process low alarm). Refer to Figure 3.3 and Figure 3.4 for the description of deviation alarm and process alarm.
Figure 3.3 Output 2 Deviation
High Alarm

Figure 3.4 Output 2 Process
Low Alarm
3-4 Alarm

The controller has one alarm output. There are 6 types of alarm functions and one dwell timer can be selected, and four kinds of alarm modes (ALMD) are available for each alarm function (ALFN). Besides the alarm output, the output 2 can also be configured as another alarm. But output 2 only provides 4 kinds of alarm functions and only normal alarm mode is available for this alarm.

A process alarm sets two absolute trigger levels. When the process is higher than SP3, a process high alarm (PV.HI) occurs, and the alarm is off as the process is lower than SP3-ALHY. When the process is lower than SP3, a process low alarm (PV_LO) occurs and the alarm is off as the process is higher than SP3+ALHY. A process alarm is independent of set point.

A deviation alarm alerts the user when the process deviates too far from set point. When the process is higher than SV+SP3, a deviation high alarm (DE.HI) occurs and the alarm is off as the process is lower than SV+SP3-ALHY. When the process is lower than SV+SP3, a deviation low alarm (DE.LO) occurs and the alarm is off as the process is higher than SV+SP3+ALHY. Trigger level of deviation alarm is moving with set point.

A deviation band alarm presets two trigger levels relative to set point. The two trigger levels are SV+SP3 and SV-SP3 for alarm. When the process is higher than (SV+SP3) or lower than (SV-SP3), a deviation band high alarm (DB.HI) occurs. When the process is within the trigger levels, a deviation band low alarm (DB.LO) occurs.

In the above descriptions SV denotes the current set point value for control which is different from SP1 as the ramp function is performed.

There are four types of alarm modes available for each alarm function, these are: Normal alarm, Latching alarm, Holding alarm and Latching/Holding alarm. They are described as follows:
Normal Alarm: ALMD = NORM
When a normal alarm is selected, the alarm output is de-energized in the non-alarm condition and energized in an alarm condition.

Latching Alarm: ALMD = LTCH
If a latching alarm is selected, once the alarm output is energized, it will remain unchanged even if the alarm condition is cleared. The latching alarm is reset when the RESET key is pressed, once the alarm condition is removed.

Holding Alarm: ALMD = HOLD
A holding alarm prevents an alarm from power up. The alarm is enabled only when the process reaches the set point value. Afterwards, the alarm performs same function as normal alarm.

Latching / Holding Alarm: ALMD = LT.HO
A latching / holding alarm performs both holding and latching function. The latching alarm is reset when the RESET key is pressed, once the alarm condition is removed.

Alarm Failure Transfer is activated as the unit enters failure mode. Alarm will go on if ON is set for ALFT and go off if OFF is set for ALFT. The unit will enter failure mode when sensor break occurs or if the A-D converter of the unit fails.

3-5 Configure User Menu
This series has the flexibility for you to select those parameters which are most significant to your application. These parameters are able to be put in the front of display sequence for ease of access.

SEL1~SEL8: Selects the parameter for view and change in the user menu.

Range: LOCK, INPT, UNIT, DP, SHIF, PB, TI, TD, O1HY, CYC1, OFST, RR, O2HY, CYC2, CPB, DB, ADDR, ALHY
When using the up-down key to select the parameters, you may not obtain all of the above parameters. The number of visible parameters is dependent on the setup condition. The hidden parameters for the specific application are also deleted from the SEL selection.
Example:
OUT2 selects DE.LO  PB= 100.0  SEL1 selects INPT
SEL2 selects UNIT  SEL3 selects PB  SEL4 selects TI
SEL5~SEL8 selects NONE  Now, the upper display scrolling becomes:

3 - 6 Ramp
The ramping function is performed during power up as well as any time the set point is changed. Choose MINR or HRR for RAMP, the unit will perform the ramping function. The ramp rate is programmed by adjusting RR. The ramping function is disabled as soon as the failure mode, the manual control mode, the auto-tuning mode or the calibration mode occurs.

Example without Dwell Timer
Select MINR for RAMP, selects C for UNIT, selects 1-DP for DP, Set RR= 10.0. SV is set to 200 C initially, and changed to 100 C after 30 minutes since power up. The starting temperature is 30 C. After power up the process is running like the curve shown below:

![Figure 3.5 RAMP Function](image)

Note: When the ramp function is used, the lower display will show the current ramping value. However it will revert to show the set point value as soon as the up or down key is touched for adjustment. The ramping value is initiated to process value either as power up or RR and /or set point are changed. Setting RR to zero means no ramp function at all.
### 3-7 Dwell Timer

Alarm output can be configured as dwell timer by selecting TIMR for ALFN. As the dwell timer is configured, the parameter SP3 is used for dwell time adjustment. The dwell time is measured in minute ranging from 0.1 to 4553.6 minutes. Once the process reaches the set point the dwell timer starts to count down until zero (time out). The timer relay will remain unchanged until time out. The dwell timer operation is shown as following diagram.

After time out the dwell timer will be restarted by pressing the RESET key.

The timer stops to count during the manual control mode, failure mode, calibration period and auto-tuning period.

![Figure 3.6 Dwell Timer Function](image)

If alarm is configured as dwell timer, ALHY and ALMD are hidden.
3 - 8 PV Shift

In certain applications it is desirable to shift the controller display value from its actual value. This can be easily accomplished by using the PV shift function.

The SHIF function will alter PV only.
Example: If process variable is reading a value of 195 degrees and needs to match another indicator reading 200. The value of +5 can be installed in the SHIFT parameter. This will now ADD a 5 degree value to current reading, allowing controller to read 200 degrees. A negative value can also be used to subtract from controller current reading.

3- 9 Digital Filter

In certain application the process value is too unstable to be read. To improve this a programmable low pass filter incorporated in the controller can be used. This is a first order filter with time constant specified by FILT parameter. The default value of FILT is 0.5 sec. before shipping. Adjust FILT to change the time constant from 0 to 60 seconds. 0 second represents no filter is applied to the input signal. The filter is characterized by the following diagram.

![Figure 3.8 Filter Characteristics](image)

**Note**
The Filter is available only for PV, and is performed for the displayed value only. The controller is designed to use unfiltered signal for control even if Filter is applied. A lagged (filtered) signal, if used for control, may produce an unstable process.
3-10 Failure Transfer

The controller will enter failure mode as one of the following conditions occurs:
1. SBER occurs due to the input sensor break or input current below 1mA if 4-20 mA is selected or input voltage below 0.25V if 1-5 V is selected.
2. ADER occurs due to the A-D converter of the controller fails.

The output 1 and output 2 will perform the failure transfer function as the controller enters failure mode.

Output 1 Failure Transfer, if activated, will perform:
1. If output 1 is configured as proportional control (PB≠0), and BPLS is selected for O1FT, then output 1 will perform bumpless transfer. Thereafter the previous averaging value of MV1 will be used for controlling output 1.
2. If output 1 is configured as proportional control (PB≠0), and a value of 0 to 100.0 % is set for O1FT, then output 1 will perform failure transfer. Thereafter the value of O1FT will be used for controlling output 1.
3. If output 1 is configured as ON-OFF control (PB=0), then output 1 will transfer to off state if OFF is set for O1FT and transfer to on state if ON is set for O1FT.

Output 2 Failure Transfer, if activated, will perform:
1. If OUT2 is configured as COOL, and BPLS is selected for O2FT, then output 2 will perform bumpless transfer. Thereafter the previous averaging value of MV2 will be used for controlling output 2.
2. If OUT2 is configured as COOL, and a value of 0 to 100.0 % is set for O2FT, then output 2 will perform failure transfer. Thereafter the value of O2FT will be used for controlling output 2.
3. If OUT2 is configured as alarm function, and OFF is set for O2FT, then output 2 will transfer to off state, otherwise, output 2 will transfer to on state if ON is set for O2FT.

Alarm Failure Transfer is activated as the controller enters failure mode. Thereafter the alarm will transfer to the ON or OFF state which is determined by the set value of ALFT.
3-11 Auto-tuning

The auto-tuning process is performed at set point. The process will oscillate around the set point during tuning process. Set a set point to a lower value if overshooting beyond the normal process value is likely to cause damage.

The auto-tuning is applied in cases of:
- Initial setup for a new process
- The set point is changed substantially from the previous auto-tuning value
- The control result is unsatisfactory

Operation:
1. The system has been installed normally.
2. Set the correct values for the setup menu of the unit.
   But don't use a zero value for PB and TI, otherwise, the auto-tuning program will be disabled. The LOCK parameter should be set at NONE.
3. Set the set point to a normal operating value or a lower value if overshooting beyond the normal process value is likely to cause damage.
4. Press and hold until \( A - T \) appears on the display.
5. Press \( A \) for at least 3 seconds. The AT indicator will begin to flash and the auto-tuning procedure is beginning.

NOTE:
The ramping function, if used, will be disabled once auto-tuning is proceeding.
The auto-tuning mode is disabled as soon as either failure mode or manual control mode occurs.
Procedures:
The auto-tuning can be applied either as the process is warming up (Cold Start) or as the process has been in steady state (Warm Start).

After the auto-tuning procedures are completed, the AT indicator will cease to flash and the unit revert to PID control by using its new PID values. The PID values obtained are stored in the nonvolatile memory.

Auto-Tuning Error
If auto-tuning fails an ATER message will appear on the upper display in cases of:

- If PB exceeds 9000 (9000 PU, 900.0 F or 500.0 C).
- or if TI exceeds 1000 seconds.
- or if set point is changed during auto-tuning procedure.

Solutions to ATER
1. Try auto-tuning once again.
2. Don’t change set point value during auto-tuning procedure.
3. Don’t set zero value for PB and TI.
4. Use manual tuning instead of auto-tuning. (See section 3-12).
5. Touch RESET key to reset ATER message.

3 - 12 Manual Tuning
In certain applications (very few) using auto-tuning to tune a process may be inadequate for the control requirement, then you can try manual tuning.

If the control performance by using auto-tuning is still unsatisfactory, the following rules can be applied for further adjustment of PID values:
<table>
<thead>
<tr>
<th>ADJUSTMENT SEQUENCE</th>
<th>SYMPTOM</th>
<th>SOLUTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>(1) Proportional Band (PB)</td>
<td>Slow Response</td>
<td>Decrease PB</td>
</tr>
<tr>
<td></td>
<td>High overshoot or Oscillations</td>
<td>Increase PB</td>
</tr>
<tr>
<td>(2) Integral Time (TI)</td>
<td>Slow Response</td>
<td>Decrease TI</td>
</tr>
<tr>
<td></td>
<td>Instability or Oscillations</td>
<td>Increase TI</td>
</tr>
<tr>
<td>(3) Derivative Time (TD)</td>
<td>Slow Response or Oscillations</td>
<td>Decrease TD</td>
</tr>
<tr>
<td></td>
<td>High Overshoot</td>
<td>Increase TD</td>
</tr>
</tbody>
</table>

Table 3.2 PID Adjustment Guide

Figure 3.9 shows the effects of PID adjustment on process response.

3-13 Manual Control

Operation:

To enable manual control the LOCK parameter should be set with NONE, then press [Hand] for 4.2 seconds [Hand] (Hand Control) will appear on the display. Release key and depress [Hand] for 3 seconds then the MAN indicator will begin to flash and the lower display will show [Hand]. The controller now enters the manual control mode. [Hand] indicates output control variable for output 1, and [Hand] indicates control variable for output 2. Now you can use up-down key to adjust the percentage values for the heating or cooling output.

The controller performs open loop control as long as it stays in manual control mode.
Exit Manual Control press [Hand] key the controller will revert to its normal display mode.
Figure 3.9 Effects of PID Adjustment
Two types of interface are available for Data Communication. These are RS-485 and RS-232 interface. Since RS-485 uses a differential architecture to drive and sense signal instead of a single ended architecture which is used for RS-232, RS-485 is less sensitive to the noise and suitable for a longer distance communication. RS-485 can communicate without error over 1 km distance while RS-232 is not recommended for a distance over 20 meters.

Using a PC for data communication is the most economic way. The signal is transmitted and received through the PC communication Port (generally RS-232). Since a standard PC can't support RS-485 port, a network adaptor (such as SNA10A) has to be used to convert RS-485 to RS-232 for a PC if RS-485 is required for the data communication. Multiple RS-485 units (up to 247 units) can be connected to one RS-232 port.

**Setup**

Enters the setup menu.
Select RTU for COMM. Set individual address as for those units which are connected to the same port.
Set the Baud Rate (BAUD), Data Bit (DATA), Parity Bit (PARI) and Stop Bit (STOP) such that these values are accordant with PC setup conditions.

**3 - 15 Process Retransmission**

The controllers support an optional ma/VDC output (retransmit) of the process variable. The program parameters to scale the ma/VDC signal are RELO and REHI, respectively for low and high scale. For example, using a 4/20 ma retransmission option to represent a temperature of 0/200 F unit would be setup as;
RELO = 0 for 4 ma equals 0 F
REHI = 200 for 20 ma equals 200 F
This output would typically go to a recorder, PLC, indicator etc.
Chapter 4 Calibration

⚠️ Do not proceed through this section unless there is a definite need to re-calibrate the controller. Otherwise, all previous calibration data will be lost. Do not attempt recalibration unless you have appropriate calibration equipment. If calibration data is lost, you will need to return the controller to your supplier who may charge you a service fee to re-calibrate the controller.

⚠️ Entering calibration mode will break the control loop. Verify that the system is acceptable to apply calibration mode.

Equipments needed before calibration:

1. A high accuracy calibrator (Fluke 5520A Calibrator recommended) with following functions:
   - 0 - 100 mV millivolt source with +/-0.005 % accuracy
   - 0 - 10 V voltage source with +/-0.005 % accuracy
   - 0 - 20 mA current source with +/-0.005 % accuracy
   - 0 - 300 ohm resistant source with +/-0.005 % accuracy

2. A test chamber providing 25 C - 50 C temperature range

3. A switching network (SWU16K, optional for automatic calibration)

4. A calibration fixture equipped with programming units (optional for automatic calibration)

5. A PC installed with calibration software FDC-Net and Smart Network Adaptor SNA10B (optional for automatic calibration)

The calibration procedures described in the following section are a step by step manual procedures.

Since it needs 30 minutes to warm up an unit before calibration, calibrating the unit one by one is quite inefficient. An automatic calibration system for small quantity as well as for unlimited quantity is available. Consult factory.
Manual Calibration Procedures

* Perform step 1 to enter calibration mode.

**Step 1.** Set the Lock parameter to the unlocked condition (LOCK=NONE).

Press and hold the scroll key until \( \text{CAL} \) appears on the display, then release the scroll key.
Press the scroll key for 2 seconds then release, the display will show \( \text{AdLo} \) and the unit enters calibration mode.

* Perform step 2 to calibrate Zero of A to D converter and step 3 to calibrate gain of A to D converter.

**Step 2.** Short the thermocouple input terminals, then press scroll key for at least 3 seconds. The display will blink a moment and a new value is obtained. Otherwise, if the display didn't blink or if the obtained value is equal to -199.9 or 199.9, then the calibration fails.

**Step 3.** Press scroll key until the display shows \( \text{AdHi} \). Send a 60 mV signal to the thermocouple input terminals in correct polarity. Press scroll key for at least 3 seconds. The display will blink a moment and a new value is obtained. Otherwise, if the display didn't blink or if the obtained value is equal to -199.9 or 199.9, then the calibration fails.

* Perform both steps 4 and 5 to calibrate RTD function (if required) for input.
Step 4: Press scroll key until the display shows \( \text{rEdL} \). Send a 100 ohms signal to the RTD input terminals according to the connection shown below:

```
    100 ohms
    |     |      |
   18   19   20

FDC-4100
FDC-8100
```

```
    100 ohms
    |     |      |
   12   13   14

FDC-7100
```

```
    100 ohms
    |     |      |
    4   5   6

FDC-9100
```

Figure 4.1 RTD Calibration

Press scroll key for at least 3 seconds. The display will blink a moment, otherwise the calibration fails.

Step 5: Press scroll key and the display will show \( \text{rEdH} \). Change the ohm's value to 300 ohms. Press scroll key for at least 3 seconds. The display will blink a moment and two values are obtained for RTDH and RTDL (step 4). Otherwise, if the display didn't blink or if any value obtained for RTDH and RTDL is equal to -199.9 or 199.9, then the calibration fails.

* Perform step 6 to calibrate offset of cold junction compensation, if required.

Step 6: Setup the equipments according to the following diagram for calibrating the cold junction compensation.

Note that a “K” type thermocouple must be used.
The temperature calibrator is configured as K type thermocouple output with internal compensation. Send a 0.00 C signal to the unit under calibration.

The unit under calibration is powered in a still-air room with temperature 25 +/-3 C. Stay at least 20 minutes for warming up. Perform step 1 stated above, then press scroll key until the display shows °C. Press up/down key to obtain 40.00. Press scroll key for at least 3 seconds. The display will blink a moment and a new value is obtained. Otherwise, if the display didn't blink or if the obtained value is equal to -5.00 or 40.00, then the calibration fails.

*Perform step 7 to calibrate gain of cold junction compensation if required.

**Step 7.** Setup the equipments same as step 6. The unit under calibration is powered in a still-air room with temperature 50 +/-3 C. Stay at least 20 minutes for warming up. The calibrator source is set at 0.00 C with internal compensation mode.
Perform step 1 stated above, then press scroll key until the display shows \[E\ JH\]. Press scroll key for at least 3 seconds. The display will blink a moment and a new value is obtained. Otherwise, if the display didn’t blink or if the obtained value is equal to -199.9 or 199.9, then the calibration fails.

This setup is performed in a high temperature chamber, hence it is recommended to use a computer to perform the procedures.

* Input modification and recalibration procedures for a linear voltage or a linear current input:

1. Remove R60(3.3K) and install two 1/4 W resistors RA and RB on the control board with the recommended values specified in the following table. The low temperature coefficient resistors should be used for RA and RB.

<table>
<thead>
<tr>
<th>Input Function</th>
<th>RA</th>
<th>RB</th>
<th>R60</th>
</tr>
</thead>
<tbody>
<tr>
<td>T/C, RTD, 0~60mV</td>
<td>X</td>
<td>X</td>
<td>3.3K</td>
</tr>
<tr>
<td>0 ~ 1 V</td>
<td>61.9K</td>
<td>3.92K</td>
<td>X</td>
</tr>
<tr>
<td>0 ~ 5V, 1 ~ 5V</td>
<td>324K</td>
<td>3.92K</td>
<td>X</td>
</tr>
<tr>
<td>0 ~ 10 V</td>
<td>649K</td>
<td>3.92K</td>
<td>X</td>
</tr>
<tr>
<td>0<del>20mA, 4</del>20mA</td>
<td>39 ohm</td>
<td>3.01 ohm</td>
<td>X</td>
</tr>
</tbody>
</table>

2. Perform Step 1 and Step 2 to calibrate the linear input zero.

3. Perform Step 3 but send a span signal to the input terminals instead of 60mV. The span signal is 1V for 0~1V input, 5V for 0~5V or 1~5V input, 10V for 0~10V input and 20mA for 0~20mA or 4~20mA input.

* Final step

Step 8. Set the LOCK value to your desired function.
Chapter 5 Specifications

**Power**
90 - 250 VAC, 47 - 63 Hz, 12VA, 5W maximum
11 - 26 VAC / VDC, 12VA, 5W maximum

**Input**

**Resolution:** 18 bits

**Sampling Rate:** 5 times / second

**Maximum Rating:** -2 VDC minimum, 12 VDC maximum.
( 1 minute for mA input )

**Temperature Effect:**
+/-1.5uV/ C for all inputs except mA input.
+/-3.0uV/ C for mA input

**Lead Resistance Effect:**
T/C: 0.2uV/ohm
3-wire RTD: 2.6 C/ohm of resistance difference of two leads.
2-wire RTD: 2.6 C/ohm of resistance sum of two leads

**Burn-out Current:** 200 mA

**Common Mode Rej:** 120dB

**Normal Mode Rej:** 55dB

**Sensor Break Detection:**
Sensor open for TC, RTD and mV inputs,
Sensor short for RTD input
below 1 mA for 4-20 mA input,
below 0.25V for 1 - 5V input,
unavailable for other inputs.

**Sensor Break Responding Time:**
Within 4 seconds for TC, RTD and mV inputs. 0.1 second for 4-20 mA and 1 - 5 V inputs.
<table>
<thead>
<tr>
<th>Type</th>
<th>Range</th>
<th>Accuracy @ 25 C</th>
<th>Input Impedance</th>
</tr>
</thead>
<tbody>
<tr>
<td>J</td>
<td>-120 C 1000 C&lt;br&gt;(-184 F 1832 F)</td>
<td>+/-2 C</td>
<td>2.2 MΩ</td>
</tr>
<tr>
<td>K</td>
<td>-200 C 1370 C&lt;br&gt;(-328 F 2498 F)</td>
<td>+/-2 C</td>
<td>2.2 MΩ</td>
</tr>
<tr>
<td>T</td>
<td>-250 C 400 C&lt;br&gt;(-418 F 752 F)</td>
<td>+/-2 C</td>
<td>2.2 MΩ</td>
</tr>
<tr>
<td>E</td>
<td>-100 C 900 C&lt;br&gt;(-148 F 1652 F)</td>
<td>+/-2 C</td>
<td>2.2 MΩ</td>
</tr>
<tr>
<td>B</td>
<td>0°C– 1800 C&lt;br&gt;(32 F –3272 F)</td>
<td>+/-2 C</td>
<td>2.2 MΩ</td>
</tr>
<tr>
<td>R</td>
<td>0°C– 1767.8 C&lt;br&gt;(32 BF –3214 F)</td>
<td>+/-2 C</td>
<td>2.2 MΩ</td>
</tr>
<tr>
<td>S</td>
<td>0°C– 1767.8 C&lt;br&gt;(32 BF –3214 F)</td>
<td>+/-2 C</td>
<td>2.2 MΩ</td>
</tr>
<tr>
<td>N</td>
<td>-250 C 1300 C&lt;br&gt;(-418 F 2372 F)</td>
<td>+/-2 C</td>
<td>2.2 MΩ</td>
</tr>
<tr>
<td>L</td>
<td>-200 C 900 C&lt;br&gt;(-328 F 1652 F)</td>
<td>+/-2 C</td>
<td>2.2 MΩ</td>
</tr>
<tr>
<td>PT100&lt;br&gt;(DIN)</td>
<td>-210 C 700 C&lt;br&gt;(-346 F 1292 F)</td>
<td>+/-0.4 C</td>
<td>1.3 KΩ</td>
</tr>
<tr>
<td>PT100&lt;br&gt;(JIS)</td>
<td>-200 C 600 C&lt;br&gt;(-328 F 1112 F)</td>
<td>+/-0.4 C</td>
<td>1.3 KΩ</td>
</tr>
<tr>
<td>mV</td>
<td>-8mV 70mV</td>
<td>+/-0.05 %</td>
<td>2.2 MΩ</td>
</tr>
<tr>
<td>mA</td>
<td>-3mA 27mA</td>
<td>+/-0.05 %</td>
<td>70.5 Ω</td>
</tr>
<tr>
<td>V</td>
<td>-1.3V 11.5V</td>
<td>+/-0.05 %</td>
<td>650 KΩ</td>
</tr>
</tbody>
</table>
**Output 1 / Output 2**

Relay Rating: 2A/240 VAC, life cycles 200,000 for resistive load.

Pulsed Voltage: Source Voltage 5V, current limiting resistance 66. Ω

### Linear Output Characteristics

<table>
<thead>
<tr>
<th>Type</th>
<th>Zero Tolerance</th>
<th>Span Tolerance</th>
<th>Load Capacity</th>
</tr>
</thead>
<tbody>
<tr>
<td>4-20 mA</td>
<td>3.8-4 mA</td>
<td>20-21 mA</td>
<td>500 max.</td>
</tr>
<tr>
<td>0-20 mA</td>
<td>0 mA</td>
<td>20-21 mA</td>
<td>500 max.</td>
</tr>
<tr>
<td>0 ~ 5 V</td>
<td>0 V</td>
<td>5 ~ 5.25 V</td>
<td>10 K min.</td>
</tr>
<tr>
<td>1 ~ 5 V</td>
<td>0.95 ~ 1 V</td>
<td>5 ~ 5.25 V</td>
<td>10 K min.</td>
</tr>
<tr>
<td>0 ~ 10 V</td>
<td>0 V</td>
<td>10 ~ 10.5 V</td>
<td>10 K min.</td>
</tr>
</tbody>
</table>

### Linear Output

Resolution: 15Bits

Output Regulation: 0.02 % for full load change

Output Settling Time: 0.1 sec. (stable to 99.9 %)

Isolation Breakdown Voltage: 1000 VAC

Temperature Effect: +/-0.01 % of SPAN / LC

### Triac ( SSR ) Output

Rating: 1A / 240 VAC

Inrush Current: 20A for 1 cycle

Min. Load Current: 50 mA rms

Max. Off-state Leakage: 3 mA rms

Max. On-state Voltage: 1.5 V rms

Insulation Resistance: 1000 Mohms min. at 500 VDC

Dielectric Strength: 2500 VAC for 1 minute
## DC Voltage Supply Characteristics (Installed at Output 2)

<table>
<thead>
<tr>
<th>Type</th>
<th>Tolerance</th>
<th>Max. Output Current</th>
<th>Ripple Voltage</th>
<th>Isolation Barrier</th>
</tr>
</thead>
<tbody>
<tr>
<td>20 V</td>
<td>+/-0.5 V</td>
<td>25 mA</td>
<td>0.2 Vp-p</td>
<td>500 VAC</td>
</tr>
<tr>
<td>12 V</td>
<td>+/-0.3 V</td>
<td>40 mA</td>
<td>0.1 Vp-p</td>
<td>500 VAC</td>
</tr>
<tr>
<td>5 V</td>
<td>+/-0.15 V</td>
<td>80 mA</td>
<td>0.05 Vp-p</td>
<td>500 VAC</td>
</tr>
</tbody>
</table>

### Alarm

**Alarm Relay:** Form C Rating
- 2A/240VAC, 200,000 cycles for resistive load.

**Alarm Functions:**
- Dwell timer, PV High / Low Alarm,
- Deviation High / Low Alarm,
- Deviation Band High / Low Alarm

**Alarm Mode:**
- Normal, Latching, Hold, Latching / Hold.

**Dwell Timer:**
- 0.1 - 4553.6 minutes

### Data Communications

**Interface:** RS-232 (1 unit), RS-485 (up to 247 units)

**Protocol:** Modbus Protocol RTU mode

**Address:** 1 - 247

**Baud Rate:** 2.4 - 38.4 Kbits/sec

**Data Bits:**
- 7 or 8 bits

**Parity Bit:**
- None, Even or Odd

**Stop Bit:**
- 1 or 2 bits

**Comm Buffer:**
- 160 bytes

### Analog Retransmission

**Functions:** Process Variable

**Output Signal:**
- 4-20 mA, 0-20 mA, 0 - 5V, 1 - 5V, 0 - 10V

**Resolution:** 15 bits

**Accuracy:**
- +/-0.05 % of span +/-0.0025 %/ C

**Load Resistance:**
- 0 - 500 ohms (for current output)
- 10 K ohms minimum (for voltage output)

**Regulation:** 0.01 % for full load change

**Settling Time:**
- 0.1 sec. (stable to 99.9 %)

**Breakdown Volts:**
- 1000 VAC min.

**Linearity Error:**
- +/-0.005 % of span

**Temp Effect:**
- +/-0.0025 % of span / C

**Saturation Low:**
- 0 mA (or 0V)

**Saturation High:**
- 22.2 mA (or 5.55V, 11.1V min.)

**Output Range:**
- 0-22.2mA(0-20mA or 4-20mA)
- 0-5.55V (0 - 5V, 1 - 5V)
- 0 - 11.1 V (0 - 10V)
**User Interface**
Display: Dual 4-digit LED Displays  
Keypad: 4 keys  
Programming Port: For automatic setup, calibration and testing  
Communication Port: Connection to PC for supervisory control

**Control Mode**
Output 1: Reverse (heating) or direct (cooling) action  
Output 2: PID cooling control, cooling P band 50~300% of PB, dead band -36.0 ~ 36.0 % of PB  
ON-OFF: 0.1 - 90.0 (F) hysteresis control (P band = 0)  
P or PD: 0 - 100.0 % offset adjustment  
PID: Fuzzy logic modified  
Proportional band 0.1 ~ 900.0 F.  
Integral time 0 - 1000 seconds  
Derivative time 0 - 360.0 seconds  
Cycle Time: 0.1 - 90.0 seconds  
Manual Control: Heat (MV1) and Cool (MV2)  
Auto-tuning: Cold start and warm start  
Failure Mode: Auto-transfer to manual mode while sensor break or A-D converter damage  
Ramping Control: 0 - 900.0 F/minute or 0 - 900.0 F/hour ramp rate

**Digital Filter**
Function: First order  
Time Constant: 0, 0.2, 0.5, 1, 2, 5, 10, 20, 30, 60 seconds programmable
Environmental & Physical

Operating Temperature: -10 C to 50 C
Storage Temperature: -40 C to 60 C
Humidity: 0 to 90 % RH ( non-condensing )
Insulation Resistance: 20 Mohms min. ( at 500 VDC )
Dielectric Strengt : 2000 VAC, 50/60 Hz for 1 minute
Vibration Resistance: 10 - 55 Hz, 10 m/s for 2 hours
Shock Resistance: 200 m/s ( 20 g )
Moldings: Flame retardant polycarbonate
Dimensions:
FDC-4100: 96mm(W) X 96mm(H) X 65mm(D), 53 mm depth behind panel
FDC-7100: 72mm(W) X 72mm(H) X 78.2mm(D), 65 mm depth behind panel
FDC-8100" 48mm(W) X 96mm(H) X 80mm(D), 65 mm depth behind panel
FDC-9100" 8mm(W) X 48mm(H) X 116mm(D), 105 mm depth behind panel

Weight : FDC-4100: 250 grams
FDC-7100: 200 grams
FDC-8100: 210 grams
FDC-9100: 150 grams

Agency Approvals
UL Pending
CSA Pending

Protective Class:
IP65 for panel with additional option
IP50 for panel without additional option
Ip20 for terminals and housing with protective cover.

EMC: EN61326
<table>
<thead>
<tr>
<th>Error Code</th>
<th>Display Symbol</th>
<th>Error Description</th>
<th>Corrective Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td>Er 04</td>
<td>Illegal setup values been used: Before COOL is used for OUT2, DIRT (cooling action) has already been used for OUT1, or PID mode is not used for OUT1 (that is PB = 0, and / or TI = 0)</td>
<td>Check and correct setup values of OUT2, PB, TI and OUT1. IF OUT2 is required for cooling control, the control should use PID mode (PB ≠ 0, TI ≠ 0) and OUT1 should use reverse mode (heating action), otherwise, don't use OUT2 for cooling control.</td>
</tr>
<tr>
<td>10</td>
<td>Er 10</td>
<td>Communication error: bad function code</td>
<td>Correct the communication software to meet the protocol requirements.</td>
</tr>
<tr>
<td>11</td>
<td>Er 11</td>
<td>Communication error: register address out of range</td>
<td>Don't issue an over-range register address to the slave.</td>
</tr>
<tr>
<td>14</td>
<td>Er 14</td>
<td>Communication error: attempt to write a read-only data or a protected data</td>
<td>Don't write a read-only data or a protected data to the slave.</td>
</tr>
<tr>
<td>15</td>
<td>Er 15</td>
<td>Communication error: write a value which is out of range to a register</td>
<td>Don't write an over-range data to the slave register.</td>
</tr>
</tbody>
</table>
| 26         | ARE            | Fail to perform auto-tuning function                                                                                                                                                                               | 1. The PID values obtained after auto-tuning procedure are out of range. Retry auto-tuning.  
2. Don't change set point value during auto-tuning procedure.  
4. Don't set a zero value for PB.  
5. Don't set a zero value for TI.  
6. Touch RESET key                                                                                                                                  |
| 29         | EEPE           | EEPROM can't be written correctly                                                                                                                                                                                  | Return to factory for repair.                                                                                                                                                                             |
| 30         | CJER           | Cold junction compensation for thermocouple malfunction                                                                                                                                                           | Return to factory for repair.                                                                                                                                                                             |
| 39         | SbEr           | Input sensor break, or input current below 1 mA if 4-20 mA is selected, or input voltage below 0.25V if 1-5V is selected                                                                                          | Replace input sensor.                                                                                                                                                                                       |
| 40         | ADER           | A to D converter or related component(s) malfunction                                                                                                                                                                | Return to factory for repair.                                                                                                                                                                             |
Warranty

Future Design Controls warranties or representations of any sort regarding the fitness for use, or the application of its products by the Purchaser. The selection, application or use of Future Design products is the Purchaser’s responsibility. No claims will be allowed for any damages or losses, whether direct, indirect, incidental, special or consequential. Specifications are subject to change without notice. In addition, Future Design reserves the right to make changes without notification to Purchaser to materials or processing that do not affect compliance with any applicable specification. Future Design products are warranted to be free from defects in material and workmanship for two years after delivery to the first purchaser for use. An extended period is available with extra cost upon request. Future Design’s sole responsibility under this warranty, at Future Design’s option, is limited to replacement or repair, free of charge, or refund of purchase price within the warranty period specified. This warranty does not apply to damage resulting from transportation, alteration, misuse or abuse.

RETURN MATERIAL AUTHORIZATION:
Please contact Future Design Controls for Return Material Authorization Number prior to returning to factory.

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